

Near-Optimal Distributed Shortest Paths and Transshipment

Ruben Becker, Andreas Karrenbauer, Sebastian Krinninger, and Christoph Lenzen

Shortest Transshipment Problem (STP)

Given:

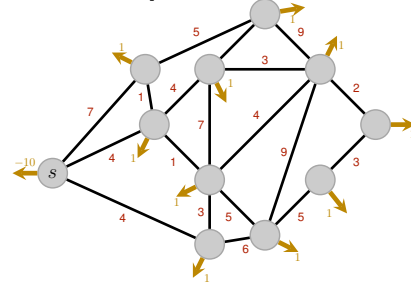
- undirected graph $G = (V, A)$, $n = |V|$
- edge weights $w \in \mathbb{N}^m$
- node demands $b \in \mathbb{Z}^n$

Goal: Ship goods from negative demand nodes to positive demand nodes, minimizing the cost.

$$\min\{\|Wx\|_1 : Ax = b\} = \max\{b^T y : \|W^{-1}A^T y\|_\infty \leq 1\}$$

Single-Source-Shortest-Path (SSSP)

Compute **shortest path** from s to all nodes (SSSP).



SSSP is the special case of STP with $b = \mathbf{1} - n\mathbf{1}_s$.

Gradient Descent Approach

Idea: Solve differentiable variant of Reciprocal LP

$$\min\{\|W^{-1}A^T \pi\|_\infty : b^T \pi = 1\}$$

using a **potential function** $\Phi_\beta(\pi) := \text{lse}_\beta(W^{-1}A^T \pi)$.

Algorithm: grad_desc

$\pi \leftarrow \alpha$ -approx., β s.t. $\Phi_\beta(\pi) \in [\frac{4 \ln(2m)}{\epsilon \beta}, \frac{5 \ln(2m)}{\epsilon \beta}]$

repeat

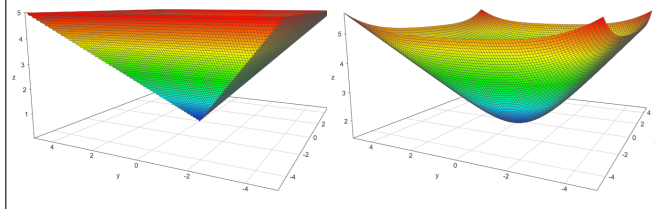
$$\begin{aligned} \tilde{b} &\leftarrow P^T \nabla \Phi_\beta(\pi), \text{ where } P \leftarrow I - \pi b^T \\ \tilde{h} &\leftarrow \alpha\text{-approx. of } \max\{\tilde{b}^T h : \|W^{-1}A^T h\|_\infty \leq 1\} \\ \delta &\leftarrow \frac{\tilde{b}^T \tilde{h}}{\|W^{-1}A^T P \tilde{h}\|_\infty} \\ \text{if } \delta > \frac{\epsilon}{8\alpha} &\text{ then } \pi \leftarrow \pi - \frac{\delta}{2\beta \|W^{-1}A^T P \tilde{h}\|_\infty} P \tilde{h}. \end{aligned}$$

until $\delta \leq \frac{\epsilon}{8\alpha}$

Here $\text{lse}_\beta(x)$ is the so-called log-sum-exp function

$$\text{lse}_\beta(x) := \frac{1}{\beta} \ln \left(\sum_{i \in [d]} \exp(\beta x_i) + \exp(-\beta x_i) \right)$$

that approx. the ∞ -norm. A 2-dim. example, for $\beta = 1$:



Results

Theorem 1: Given α -oracle for STP, one can compute solutions x, y for STP s.t. $\|Wx\|_1 \leq (1 + \epsilon)b^T y$ with $\tilde{O}(\epsilon^{-3}\alpha^2)$ oracle calls.

Theorem 2: Can compute solution y for SSSP s.t. $\frac{y_v^*}{1+\epsilon} \leq y_v \leq y_v^*$ for each v with $\text{polylog}(n, \|w\|_\infty)$ calls to grad_desc.

Implementing this framework with an oracle that computes an **optimal solution on an α -spanner** of G yields the following results.

Results in Distributed/Streaming Models:

1. **Broadcast congest:** $(1 + \epsilon)$ -approx. SSSP in $\tilde{O}(\epsilon^{-O(1)}(\sqrt{n} + D))$ rounds
2. **Broadcast congested clique:** $(1 + \epsilon)$ -approx. STP and SSSP in $\tilde{O}(\epsilon^{-O(1)})$ rounds.
3. **Multipass streaming:** $(1 + \epsilon)$ -approx. STP and SSSP in $\tilde{O}(n)$ space and $\tilde{O}(\epsilon^{-O(1)})$ passes.

Note that the upper bound for the **Broadcast Congest model** is the first to match the well-known lower bound of $\Omega(\sqrt{n}/\log n + D)$ up to logarithmic factors.

References

[BKLL16] Ruben Becker, Andreas Karrenbauer, Sebastian Krinninger, and Christoph Lenzen. *Near-Optimal Approximate Shortest Paths and Transshipment in Distributed and Streaming Models*. 2016.

